

Detection of Face with Face Recognition

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Abstract: The face is one of the simplest ways to differentiate one another's personality. Face recognition is an authentication system that uses a person's personal identity characteristics. The method of face recognition for humans consists basically of two steps, including facial recognition. The next stage is the identification of humans, where this process happens very rapidly, except in cases when the target is located a short distance away. Stage is replicated and developed as a standard for identification of facial expressions (facial recognition) is one of the long-studied developments of biometrics and developed by experts. There are two kinds of methods; Eigen face and Fisher face methods, which are common in developed trends for face recognition. Facial image recognition Identify the mechanism by way of Principal Component Analysis (PCA) for facial features to minimize the facial volume. The main purpose of using PCA for facial identification using Eigen faces was to identify a prophetic vector which corresponds to the largest value of the facial image. The area of this project is the image processing of face detection system with face recognition. The appropriate software is MATLAB software for this project.

Keywords: Eigen Face, Face Detection, MATLAB, PCA, Photometric

INTRODUCTION

The question in face recognition, on the other hand, is to assess whether a face is a person known or unknown, using a database of face to confirm this input image. Facial identification is the function to recognize an already identified object as either a known or unknown face[1], [2]. The identification of the face requires splitting the picture windows into two classes: one of the faces. It is complicated, as though there are commonalities between faces, the age, skin colors and facial expression can vary significantly[3], [4]. Different lighting conditions, image quality and geometries and the ability to refract light and cover up the problem are further simplifying this issue. Therefore, under any set of lighting conditions, any face could be detected on any background under the ideal face detector. The process of face detection might be separated into two steps. The first step is to define a subjective image, which takes an image as a binary value of "yes" or "no," implying whether there are faces in the image[5], [6]. The second step is to identify the image as input and output, as boxes with (x, y, height, width), the

position of the faces of any face or faces inside this frame.

The face detection device can be classified into:-

Pre-Processing:

The photographs are scanned before they are inserted into the network in order to minimize variability in faces. The positive representations of facial pictures are produced only through cropping images of frontal view. Both images are then corrected by regular algorithms for lighting

Classification:

Neural networks are formed to categorize pictures as nonfaces or faces, through training them. For this reason, we use the neural network implementation as well as the MATLAB neural networking toolbox. To maximize performance, different network structures are played with.

Localization: The qualified neural network is then used to locate face in an image and to place it in a

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bounding box while current. Various Face features on which the research on Place Scale Illumination has been perform.

1. *Digital Image Processing*

Digital image processing priorities come from two principal areas of application:

- Enhancement of human perception pictorial information, processing scene data on autonomous machine perception, the focus on procedures for the extraction of the image information in a computer-appropriated format is in this second field of application[7], [8]. Types include automated identification of character, industrial machine vision to assemble and test the component, military recognition, fingerprint automation, etc.
- Image: In the image the 2D light intensity function $f(x, y)$ is referred to where (x, y) refers to spatial coordinates; at any point f values (x, y) are proportional to the image brightness and gray levels. A digital image is an $f(x, y)$ image that is discretized, both spatially and luminously. Picture components or pixels are considered the elements in such a digital array.
- A simple image model: A picture $f(x, y)$ should be digitized in both space and amplitude to be suitable for computer processing. Spatial coordinate digitalization (x, y) is known as image sampling. The digitization of amplitude is called the quantification of the gray point[9], [10]. With the spatial resolution and the amount of gray shades, capacity and computational demands rapidly increase. Example: A 256 grayscale 256x256 image occupies a memory of 64k bytes.

2. *Image processing types:*

- Low level processing : The low-level treatment means the performance of basic operations on images such as reading an image resize, rotate, Image Rotations, RGB

conversion to gray level, histogram equalization, etc.

- Medium level processing: Medium-level processing is the separation of regions of interest from the output of the low-level image processed. Medium-level distributed processing deals with the recognition of boundaries i.e. edges. The whole process is known as segmentation.
- High level processing: High-level processing involves the addition of artificial intelligence to the processed medium level signal.

3. *Image Processing Fundamental Steps:*

The steps are follows:

- *Image acquisition:* digital image acquisition
- *Pre-processing image:* to increase the image in a way this increases chances of other processes working.
- *Segmentation of images:* divisions of an input image into its object constituents.
- *Segmentation of image:* to translate input data into computer-friendly information.
- *Image description:* to collect characteristics resulting in certain quantitative data of importance of the characteristics necessary for the classification of one type of objects.
- *Recognition of image:* attach a mark to an object on the basis of its description information.

4. *MATLAB:*

The MATLAB name means the LaboratoryMatrix. Initially MATLAB was designed for easy access by EISPACK (Eigen system package) and LINPACK (linear system package) projects to matrix software. MATLAB is an advanced technical programming language. This incorporates the environment of computation, programming and visualization. In MATLAB, the advantages of addressing technical problems are substantial in contrast with traditional computer languages (e.g. C, FORTRAN). MATLAB is an interactive framework with a fundamental data aspect which needs no dimensioning. In packages

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known as the toolbox, specific applications are collected. The toolboxes for signal processing, control theory, symbolic computation, optimization, simulation and several other areas in computer science and engineering are available.

4.1. MATLAB's Power in Computational Mathematics:

In all areas of computational mathematics the MATLAB is used. Some of the widely used equations indicate where it is most frequently found. The following are:

- Linear Algebra
- Dealing with Arrays and Matrices
- Various other special functions
- 2-D and 3-D graphics and Plotting
- Differential and Calculus Equations
- Numerical Calculations
- Algebraic Equations
- Non-linear Functions
- Statistics
- Integration
- Transforms
- Data Analysis
- Curve Fitting

4.2. MATLAB Features:

The basic functions in MATLAB are below. This is widely used to visualize, calculate numerically and build the specification.

- It also gives an interactive environment to explore, design and solve problems.
- It offers an extensive mathematical library for linear algebra, Fourier analytics, statistics, filters, numerical integration, optimization and the resolution of standard differential equations.
- It offers advanced graphics to display data and tools for the creation of custom plots.
- The programming interface from MATLAB offers tools for the development of improved code efficiency, maintenance and performance.
- It provides tools for designing custom graphical interfaces applications.

- It provides features to combine algorithms based on MATLAB with other programs and languages such as C, Microsoft Excel, Java and .NET.

4.3. Uses of MATLAB:

For science and engineering, the MATLAB is commonly used as a computing tool comprising physics, chemistry, mathematics and all engineering sources. It is used in a number of applications, such as:

- Computational finance
- Measurement and test.
- Communications and signal processing.
- Control systems
- Computational biology
- Video Processing and image.

5. Face Detection:

The facial recognition issue is all about facial identification. This is a strange reality for new scientists in this area. Nevertheless, one must be able to reliably identify a face and its landmarks before facial recognition is feasible. For functional systems the bulk of the effort goes to solving this function. It is basically a segmentation problem. The actual recognition based on characteristics extracted from these facial points is in fact only a minor final step. There are two types of problems with face detection:

- 1) Face detection in the images
- 2) Face detection in real time.

5.1. Images Face Detection:

Many facial detection devices try to remove a fraction of the entire face, removing the most portion of the background and other parts of the eyes, such as eyebrows, not required for facial recognition. This is often achieved by running through the picture of static images. This ensures that the facial detection system checks if a person is in the camera. For static pictures there is sadly an extremely large search area in a photo for potential destinations. A face invariant is a facial recognition scheme compatible with

matching templates. This makes it possible to build a room template of the face that closely corresponds to the facial characteristics, using the local ordinal structure of a face brightness distribution remains largely unchanged under different lighting conditions. In other words, the maximum gray color on human faces is used for face detection. For examples, a person's eye area is almost always darker than his forehead or nose. A picture thus fits the prototype if it follows the relationships "darker than" and "brighter than." Fig 1 shows the face detection process.

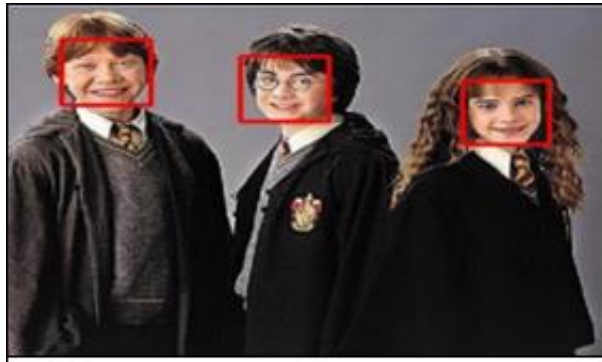


Figure 1: The Figure Shows the Face Detection Process

6. *Face Detection in Real-Time:*

Real-time identification of the face requires the detection of the face from a video recorder. While the hardware requirements of such an instrument are far tougher, in fact, real-time face detection is a much simpler process than the identification of a face in a static picture from a computer vision level. This is because people are constantly traveling, unlike most of our surroundings. People are walking around, blinking, waving, fidgeting etc.

7. *Face Detection Process:*

This method can be accomplished using MATLAB codes. In that experiment, the author tries to identify faces in still photographs by using image invariants. This procedure distinguishes various parts of human face like the eyes, nose, mouth, etc. In doing that, the grayscale color spectrum of an average human face would be beneficial to research. A sample of thirty

face-sides of human beings, 12 of which were women and 18 of male, consisted of the "average human face." To display gray intensity variations, an effective color map was used. There are surprising variations in gray scale, which are invariant across all sample faces. The eyepiece always seems to be dark (low) gray while the front and cheeks of the nose have (high) grey-levels of brightness. The scientist discovered that the following sections of the human face are ideal after much experimenting for a vision detection system focused on image variations and a deformable prototype.

8. *Face Recognition:*

Many techniques for face recognition were suggested in recent decades. Many of the techniques proposed in the early stages of computer vision are not considered successful, but nearly all new approaches to the problem of face recognition are credible. Research has shown that every approach to recognition of the human face can be divided into two strategies:

- (1) Matching templates
- (2) Geometric features.

9. *Geometrical Features Face Recognition:*

This technique involves the estimation from the image of a face individual want to remember of certain anatomical features such as mouth location, nose width and length and chin shape, etc. That set of characteristics is then paired with characteristics of recognized individuals. The nearest match can be made using an appropriate calculation such as a Euclidean distance (find the nearest vector). The most groundbreaking work was done using geometrical characteristics to distinguish the face. The drawback of using geometrical characteristics as a basis for face recognition is that even at very low resolution and noisy pictures (images with many distracting pixel intensities) are remembered. Although its overall geometrical configuration cannot be seen in detail, it is possible to extract its face for identification. The main disadvantage of the procedure is the fact that it

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is very difficult to automate facial geometric elimination. Automated geometrical extraction-based identification for the rotation and scaling of the image plane is also very sensitive. This is apparent when researchers investigate results where a recognition rate of only 20 people has been reported for 45-75 percent. Nonetheless, a sufficient outcome can be achieved if these functions are selected manually.

10. System Specification and Problem Scope:

After a study of the face and face recognition literature and the probability of real world situations for these technologies, the following issue spectrum was identified for this project. The system specifications have been identified:

- A frontal view detection system for static images
- A program to identify a given frontal view face.
- The face recognition and detection is presented only with expressionless front faces.
- A high degree of in variety of light is needed in all systems implemented.
- Each machine needs to perform almost in real time.
- It must be supported both in fully manual face and automated detection.
- Only a single known image will be used to define the face of front view.
- Automation of face detection and recognition applications into a fully recognition system and automated face detection should be implemented. The sub-system for the identification of the face has to be marginally invariant in the segmented

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images of the face detection subsystem to rotation errors and scaling.

- The facial face recognition system in the forward view must be applied to a face recognition system that is invariant. Unfortunately, even if it can define restrictive criteria for our region of question, these conditions cannot be exclusively followed when applying a real-life system.

CONCLUSION

The computer models applied in this project were chosen after extensive research and successful test results indicate that the researcher made accurate choices. Because of the small number of individual faces used for PCA transform, a device with the manual facial sensor and automatic facial sensitivity did not exceed 90% had a consistency of identification. In this experimental study this system was performed in extremely robust conditions and real-world results is supposed to be far more reliable. The completely automated front visual facial detection system was almost successful and further testing in this area does not need to be undertaken in the researcher's view. For fact, there was no expressionless facial vision for many of the test subjects to the system. It would be more compliant when a policeman of 6'5" is having their mugshot! Full identification or an identical match is also not a requirement for mugshot matching applications. If a face recognition device would reduce the amount of pictures that a human operator has to identify from 10000 to even 100, it would be incredibly useful in law enforcement. The automatic vision methods introduced in this study have not even been as stable as the inborn facial recognition method of a person. Nevertheless, they provide a glimpse into what computer vision will bring in the future.

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